

. 1.

1.

	x_1	x_2	...	x_p
K_1	O_{11}	O_{12}	...	O_{1p}
K_2	O_{21}	O_{22}	...	O_{2p}
\vdots				
K_m	O_{m1}	O_{m2}	...	O_{mp}

$$O_{ij} = (O_{ij}), i = 1, \dots, m; j = 1, \dots, p, \quad (1)$$

$\{K_1, K_2, \dots, K_h\} \subseteq K$
 $(i = 1, 2, \dots, p), \quad \varepsilon_i -$

2.

x_i	ε_1	ε_2	...	ε_l
K_1	Q_{11}^i	Q_{12}^i	...	Q_{1l}^i
K_2	Q_{21}^i	Q_{22}^i	...	Q_{2l}^i
\vdots				
K_h	Q_{h1}^i	Q_{h2}^i	...	Q_{hl}^i

$$Y(s) = a + bs, \quad [1]: \quad s = l+1, \quad (2)$$

$$Y_g^i(s) = a_g^i + b_g^i s, \quad i = \overline{1, p}, \quad g = \overline{1, h}. \quad (3)$$

b_g^i, a_g^i [2]:

$$b_g^i = \frac{l \cdot \sum_{k=1}^l \varepsilon_k \cdot Q_{gk}^i - \sum_{k=1}^l \varepsilon_k \cdot \sum_{k=1}^l Q_{gk}^i}{l \cdot \sum_{k=1}^l \varepsilon_k^2 - \left(\sum_{k=1}^l \varepsilon_k \right)^2}, \tag{4}$$

$$a_g^i = \overline{d}_g^i - b_g^i \cdot \overline{q}, \tag{5}$$

$$\overline{d}_g^i = \frac{1}{l} \sum_{k=1}^l Q_{gk}^i, \quad \overline{q} = \frac{1}{l} \sum_{k=1}^l \varepsilon_k, \quad i = \overline{1, p}, \quad g = \overline{1, h}.$$

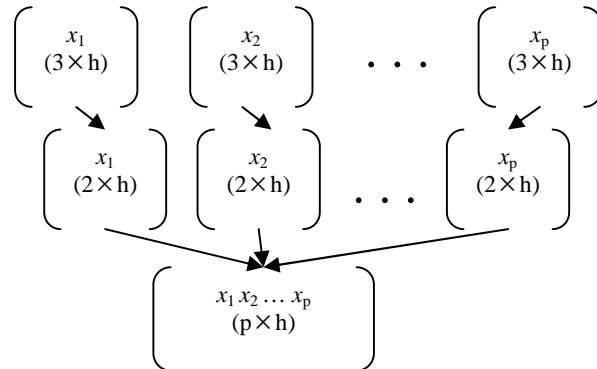
$$s = l+1, \quad s = l+2, \quad s = l+3$$

, .3.

3.

x_i	$l+1$	$l+2$	$l+3$
K_1	$Y_1^i(l+1)$	$Y_1^i(l+2)$	$Y_1^i(l+3)$
K_2	$Y_2^i(l+1)$	$Y_2^i(l+2)$	$Y_2^i(l+3)$
\vdots			
K_h	$Y_h^i(l+1)$	$Y_h^i(l+2)$	$Y_h^i(l+3)$

$$L_i = \left(Y_g^i(l+k) \right), \quad i = \overline{1, p}; \quad g = \overline{1, h}; \quad k = \{1, 2, 3\}. \tag{6}$$



.....

..... (3×h),

[3]:

$$T_g^i(1) = \frac{Y_g^i(l+2)}{Y_g^i(l+1)}, \tag{7}$$

$$T_g^i(2) = \frac{Y_g^i(l+3)}{Y_g^i(l+2)}, \tag{8}$$

$i = \overline{1, p}, g = \overline{1, h}$.

(2×h)

:

$$T_i = \left(T_g^i(\alpha) \right), i = \overline{1, p}; g = \overline{1, h}; \alpha = \{1, 2\}. \tag{9}$$

. 4.

4.

x_i	$T(1)$	$T(2)$
K_1	$T_1^i(1)$	$T_1^i(2)$
K_2	$T_2^i(1)$	$T_2^i(2)$
\vdots		
K_h	$T_h^i(1)$	$T_h^i(2)$

.....

(9)

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» (.....),

[3]:

$$A_g^i = \sqrt{T_g^i(1) \cdot T_g^i(2)}, \tag{10}$$

$i = \overline{1, p}, g = \overline{1, h}$.

. 5.

5.

	x_1	x_2	...	x_p
K_1	A_1^1	A_1^2	...	A_1^p
K_2	A_2^1	A_2^2	...	A_2^p
\vdots				
K_h	A_h^1	A_h^2	...	A_h^p

$$A = (A_g^i), \quad i = \overline{1, p}; \quad g = \overline{1, h}. \quad (11)$$

(11),

[4, 5],

$$\ll \quad \gg [4, 5] \quad T = (t_1, t_2, \dots, t_h),$$

«

»

(11)

«

» T,

$$z_{gi} = 1 - \frac{|t_g - A_g^i|}{\max\{t_g - \min_i A_g^i; \max_i A_g^i - t_g\}}, \quad g = \overline{1, h}; \quad i = \overline{1, p}. \quad (12)$$

(11)

«

».

$$Z = \{z_{gi}\}$$

«

»

$$\{p_1, p_2, \dots, p_h\}$$

[1, a].

:

$$\alpha_g = \frac{p_g}{\sum_{g=1}^h p_g}, \quad g = \overline{1, h}; \quad \alpha_g \in [0, 1]; \quad \sum_{g=1}^h \alpha_g = 1. \quad (13)$$

... , ... , ... [6].

$$A(x_i) = \sum_{g=1}^h \alpha_g z_{gi}, i = \overline{1, p}. \quad (14)$$

$$X = \{x_1, x_2, \dots, x_p\}. \quad (15)$$

... , ... , ...
 x_1, x_2, x_3
 [7]
 2010 – 2013 . (. 6).

6.

		(p)	()
K_1		8	1,10
K_2		9	1,05
K_3		7	1,10
K_4		10	1,00

... , 7.

7. – x_1, x_2, x_3

-	x_1				x_2				x_3			
	2010	2011	2012	2013	2010	2011	2012	2013	2010	2011	2012	2013
K_1	0,4	1,1	0,6	0,7	0,3	1,2	1,3	0,9	0,5	0,1	0,6	0,7
K_2	0,8	1	1,2	1,3	0,8	0,9	1,2	1	1,4	1	1,6	1,3
K_3	0,9	2,9	4,1	1,8	0,5	0,9	2,1	1,1	1,9	3,0	3,2	1,9
K_4	0,06	0,09	0,12	0,07	0,06	0,07	0,06	0,05	0,1	0,04	0,05	0,06

...

$$K_1 \cdot \quad (4) \quad (5) \quad \quad \quad x_1 \quad b_1^1, a_1^1 :$$

$$b_1^1 = \frac{4 \cdot 5632,4 - 8046 \cdot 2,8}{4 \cdot 16184534 - 8046 \cdot 8046} = 0,04, \quad a_1^1 = \frac{1}{4} \cdot 2,8 - 0,04 \cdot \frac{1}{4} \cdot 8046 = -79,76.$$

$$, \quad (3) \quad :$$

$$Y_1^1(s) = -79,76 + 0,04 \cdot s.$$

2016 K_1 2014, 2015, :

$$Y_1^1(2014) = -79,76 + 0,04 \cdot 2014 = 0,8;$$

$$Y_1^1(2015) = -79,76 + 0,04 \cdot 2015 = 0,84;$$

$$Y_1^1(2016) = -79,76 + 0,04 \cdot 2016 = 0,88.$$

11

2014, 2015, 2016

. 8.

8.

- x_1, x_2, x_3

	x_1			x_2			x_3		
	2014	2015	2016	2014	2015	2016	2014	2015	2016
K_1	0,8	0,84	0,88	1,4	1,59	1,78	0,75	0,86	0,97
K_2	1,5	1,67	1,84	1,2	1,29	1,38	1,4	1,43	1,46
K_3	3,4	3,79	4,18	1,9	2,2	2,5	2,55	2,57	2,59
K_4	0,11	0,12	0,13	0,06	0,06	0,06	0,038	0,027	0,018

, (7) (8), . 9.

9.

	x_1		x_2		x_3	
K_1	1,050	1,048	1,136	1,119	1,147	1,128
K_2	1,113	1,102	1,075	1,070	1,021	1,021
K_3	1,115	1,103	1,158	1,136	1,008	1,008
K_4	1,091	1,083	1,000	1,000	0,711	0,667

. 2015, 1

.....

() (10),
 . 10.

10.

	x_1	x_2	x_3
K_1	1,049	1,128	1,137
K_2	1,108	1,072	1,021
K_3	1,109	1,147	1,008
K_4	1,087	1,000	0,688

(12)

$Z = \{ z_{gi} \}$:

$$Z = \begin{pmatrix} 0,00 & 0,46 & 0,27 \\ 0,00 & 0,61 & 0,50 \\ 0,90 & 0,49 & 0,00 \\ 0,72 & 1,00 & 0,00 \end{pmatrix}$$

(13)

$\alpha = (0,24; 0,26; 0,21; 0,29).$

:

(14)

$A = (0,4; 0,67; 0,2).$

$\{ x_2, x_1, x_3 \}.$

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N. Malyar, V. Polishchuk, M. Sharkadi

USING DYNAMIC CRITERIA IN THE MODELS OF MULTICRITERIA CHOICE

The paper proposes a new approach to the problem of multi-choice alternatives, based on the use of dynamic performance criteria, given their tendency and rate of growth. The essence of this approach is that if there are performance criteria, for which the values of estimates of alternatives are known for certain prior periods, then it is possible to predict their scores thereafter. Thus, when making a decision, an opportunity to consider an expected behavior appears.

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