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**ON SOME PERTURBATIONS OF A SYMMETRIC STABLE PROCESS
 AND THE CORRESPONDING CAUCHY PROBLEMS**

A semigroup of linear operators on the space of all continuous bounded functions given on a d -dimensional Euclidean space \mathbb{R}^d is constructed such that its generator can be written in the following form $\mathbf{A} + (a(\cdot), \mathbf{B})$, where \mathbf{A} is the generator of a symmetric stable process in \mathbb{R}^d with the exponent $\alpha \in (1, 2]$, \mathbf{B} is the operator that is determined by the equality $\mathbf{A} = c \operatorname{div}(\mathbf{B})$ ($c > 0$ is a given parameter), and a given \mathbb{R}^d -valued function $a \in L_p(\mathbb{R}^d)$ for some $p > d + \alpha$ (the case of $p = +\infty$ is not exclusion). However, there is no Markov process in \mathbb{R}^d corresponding to this semigroup because it does not preserve the property of a function to take on only non-negative values. We construct a solution of the Cauchy problem for the parabolic equation $\frac{\partial u}{\partial t} = (\mathbf{A} + (a(\cdot), \mathbf{B}))u$.

INTRODUCTION

A d -dimensional symmetric stable process (α -stable process) is a Markov process in \mathbb{R}^d with its transition probability density given by

$$g(t, x, y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \exp \{i(y - x, \xi) - ct|\xi|^\alpha\} d\xi, \quad t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$$

(parameters $c > 0$ and $\alpha \in (1, 2]$ will be fixed throughout this article). As is well known, the generator \mathbf{A} of this process is a pseudo-differential operator, whose symbol is given by the expression $(-c|\lambda|^\alpha)_{\lambda \in \mathbb{R}^d}$. The parameter α is called the exponent of this process.

A Wiener process is a particular case of a symmetric stable process, if we put $\alpha = 2$ and $c = 1/2$. Its generator is the Laplace operator (with the multiplier $1/2$). The perturbation of this operator by means of the operator (a, ∇) , where $(a(x))_{x \in \mathbb{R}^d}$ is some \mathbb{R}^d -valued function, ∇ is the Hamilton operator (gradient) and (\cdot, \cdot) denotes the scalar product in \mathbb{R}^d , allows us to construct the diffusion process with the drift vector a . A great deal of publications considered perturbations under some more or less general assumptions on the function a (see, for example, [5] and the references therein).

This article is devoted to the perturbing a symmetric stable process with $\alpha \in (1, 2)$ in a similar way. In our situation the operator \mathbf{B} , with its symbol $(i|\lambda|^{\alpha-2}\lambda)_{\lambda \in \mathbb{R}^d}$, is an analogue to the gradient. The role of this operator in the theory of potentials for symmetric stable processes is discussed in the paper [9].

Symmetric stable processes were perturbed by terms of the type (a, ∇) under various assumptions on the function a in many papers (see, for example, [2, 4, 10, 11]). The perturbation of stable processes with delta-function in coefficient is constructed in [6, 8]. The operator \mathbf{B} used in perturbations of stable processes in the papers [6, 7, 8].

This paper is organized as follows. In the next section we present the basic concepts and preliminary results. Section 2 contains the construction of the stable process perturbation and the investigation of some its properties. And the final Section 3 is devoted to the Cauchy problem for the pseudo-differential equation of parabolic type with operator $\mathbf{A} + (a, \mathbf{B})$ on the spatial variable.

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1. NOTATION AND AUXILIARY RESULTS

Let F_γ ($\gamma > 0$) be the class of functions $\varphi(x)$ defined on \mathbb{R}^d with values in \mathbb{R} , which are the Fourier transforms $\varphi(x) = \int_{\mathbb{R}^d} e^{i(x,\lambda)} \Phi(\lambda) d\lambda$ and such that the functions $|\lambda|^\gamma \Phi(\lambda)$ are absolutely integrable on \mathbb{R}^d .

Recall that the operator \mathbf{A} acting on the functions $\varphi \in F_\alpha$ according to the following rule $\mathbf{A}\varphi(x) = -c \int_{\mathbb{R}^d} |\lambda|^\alpha e^{i(x,\lambda)} \Phi(\lambda) d\lambda$ and the equality $\mathbf{B}\varphi(x) = \int_{\mathbb{R}^d} i|\lambda|^{\alpha-2} \lambda e^{i(x,\lambda)} \Phi(\lambda) d\lambda$ is true for functions $\varphi \in F_{\alpha-1}$. It is easy to see that the equality $\mathbf{A} = c \operatorname{div}(\mathbf{B})$ holds on F_α , where div is the divergence operator.

Let $(a(x))_{x \in \mathbb{R}^d}$ be a some given \mathbb{R}^d -valued measurable function.

Definition 1.1. A function $(G(t, x, y))_{t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d}$ is called a result of perturbing the transition probability density $g(t, x, y)$, if it is a solution of the following equation

$$(1) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) (a(z), \mathbf{B}_z G(\tau, z, y)) dz.$$

The subscript of operator \mathbf{B} (here and in what follows) means that it acts on a function of several variables in the indicated variable.

We will construct the solution of equality (1) in the form

$$(2) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz,$$

where the function $V(t, x, y)$ satisfies the equation

$$(3) \quad V(t, x, y) = V_0(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V(\tau, z, y) |a(z)| dz$$

and

$$(4) \quad V_0(t, x, y) = (\mathbf{B}_x g(t, x, y), e(x)) = \frac{1}{c\alpha} \frac{(y - x, e(x))}{t} g(t, x, y).$$

Here we use a function $(e(x))_{x \in \mathbb{R}^d}$ defined by the equality $e(x) = \frac{1}{|a(x)|} a(x)$ for $x \in \mathbb{R}^d$ such that $|a(x)| \neq 0$ and an arbitrary value (with preservation of the measurability) otherwise.

Equation (3) can be solved by the method of successive approximations, namely its solution will be found in the form

$$(5) \quad V(t, x, y) = \sum_{k=0}^{\infty} V_k(t, x, y),$$

where $V_0(t, x, y)$ is defined by equality (4) and for $k \geq 1$ the following equality

$$V_k(t, x, y) = \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V_{k-1}(\tau, z, y) |a(z)| dz$$

is valid.

We will use some inequalities that are proved in the article [3].

The first inequality is

$$(6) \quad g(t, x, y) \leq N \frac{t}{(t^{1/\alpha} + |y - x|)^{d+\alpha}},$$

where $N > 0$ is a constant, $t > 0$, $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$.

The following inequality will be used in various situations

$$(7) \quad \int_0^t d\tau \int_{\mathbb{R}^d} \frac{(t-\tau)^{\beta/\alpha}}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha+k}} \frac{\tau^{\gamma/\alpha}}{(\tau^{1/\alpha} + |y-z|)^{d+\alpha+l}} dz \leq \\ \leq C \left[B\left(\frac{\beta-k}{\alpha}, 1 + \frac{\gamma}{\alpha}\right) t^{\frac{\beta+\gamma-k}{\alpha}} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha+l}} + \right. \\ \left. + B\left(1 + \frac{\beta}{\alpha}, \frac{\gamma-l}{\alpha}\right) t^{\frac{\beta+\gamma-l}{\alpha}} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha+k}} \right],$$

that is true for some constants β, γ, k, l , satisfying the conditions: $-\alpha < k < \beta$, $-\alpha < l < \gamma$, and $C > 0$ which depends only on d, α, k and l . Here $B(\cdot, \cdot)$ is Euler beta function.

We shall also use below the following result (see, for example, [3]). Denote by $C_b(D)$ the space of all continuous bounded real-valued functions on the set D . Let $\varphi \in C_b(\mathbb{R}^d)$ and $(f(t, x))_{t \geq 0, x \in \mathbb{R}^d}$ be a continuous function bounded on each domain of the form $D_T = [0, T] \times \mathbb{R}^d$ for $T < +\infty$. We suppose that the function f is Hölder continuous (with an arbitrary coefficient from the interval $(0, 1)$) in the argument x locally uniformly with respect to t . Then the unique bounded solution of the Cauchy problem

$$(8) \quad \begin{cases} \frac{\partial u(t, x)}{\partial t} = \mathbf{A}_x u(t, x) + f(t, x), & t > 0, x \in \mathbb{R}^d, \\ \lim_{t \rightarrow 0+} u(t, x) = \varphi(x), & x \in \mathbb{R}^d \end{cases}$$

can be written as follows

$$u(t, x) = \int_{\mathbb{R}^d} g(t, x, y) \varphi(y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) f(\tau, z) dz.$$

2. THE PERTURBATION

In this section we will prove existence of the perturbation (in the sense of Definition 1.1) by operator \mathbf{B} with the function a satisfies some integrability condition. A few properties of this perturbation will be established below.

Theorem 2.1. *Let the function $(a(x))_{x \in \mathbb{R}^d}$ satisfies the following condition: $a \in L_p(\mathbb{R}^d)$ with $p > d + \alpha$ (maybe, $p = +\infty$).*

Then the perturbation $G(t, x, y)$ (see Definition 1.1) exists and possesses the following properties

(i) *It satisfies the Kolmogorov-Chapman equation*

$$\int_{\mathbb{R}^d} G(t, x, z) G(s, z, y) dz = G(t + s, x, y), \quad t > 0, s > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d;$$

(ii) *It is absolutely integrable and $\int_{\mathbb{R}^d} G(t, x, y) dy \equiv 1$.*

Proof. Formulas (4), (6), and (7) allows us to write down the inequality

$$(9) \quad |V_0(t, x, y)| \leq \frac{N}{c\alpha} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$$

Then the following inequality is true for all $k \in \mathbb{N}$ and $t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$

$$|V_k(t, x, y)| \leq \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{1}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha-1}} |V_{k-1}(\tau, z, y)| |a(z)| dz$$

Using inequality (7) one can show by induction on k that the function V_k for $k = 0, 1, 2, \dots$ satisfies the inequality

$$\begin{aligned} |V_k(t, x, y)| &\leq \|a\|_p^k \left(\frac{N}{c\alpha}\right)^{k+1} C^{k\nu} R_k \frac{t^{k\frac{\rho}{\alpha}}}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}} \leq \\ &\leq \|a\|_p^k \left(\frac{N}{c\alpha}\right)^{k+1} C^{k\nu} R_k t^{(k\rho-d+1)\frac{1}{\alpha}-1}, \end{aligned}$$

where $\nu = 1 - \frac{1}{p}$, $\rho = 1 - \frac{d}{p}$, $R_0 = 1$, $R_k = R_{k-1} \left(B \left(\frac{p-d-\alpha}{\alpha(p-1)}, 1 + (k-1) \frac{p-d}{\alpha(p-1)} \right) + B \left(1, \frac{p-d-\alpha}{\alpha(p-1)} + (k-1) \frac{p-d}{\alpha(p-1)} \right) \right)^{1-\frac{1}{p}}$ (or limits of these expressions when p tends to infinity, if $p = +\infty$).

Therefore, the series on the right hand side of (5) converges uniformly in $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$ and locally uniformly in $t > 0$. Thus, the function V given by this equality is a solution of equation (3). In addition, the following inequality

$$(10) \quad |V(t, x, y)| \leq C_T \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$$

has been proved for $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$ and $0 < t \leq T$, where C_T is a positive constant that, maybe, depends on $T > 0$.

Remark 2.1. The function $V(t, x, y)$ is the unique solution of equation (3) in the class of functions that satisfy inequality (10).

Finally, since the equality $(\mathbf{B}_x G(t, x, y), \epsilon(x)) = V(t, x, y)$ holds, the function

$$(11) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz,$$

is the perturbation of the transition probability density of the α -stable process.

Here we have used the following statement.

Lemma 2.1. *The equality $\mathbf{B}_x \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz = \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz$ is true.*

The proof of this lemma is based on the following representation of the operator \mathbf{B} : $\mathbf{B}\varphi(x) = \frac{1}{\varkappa} \int_{\mathbb{R}^d} \frac{\varphi(x+y) - \varphi(x)}{|y|^{d+\alpha}} y dy$ for a bounded differentiable function $(\varphi(x))_{x \in \mathbb{R}^d}$, where $\varkappa = -\frac{2\pi^{\frac{d-1}{2}} \Gamma(2-\alpha) \Gamma(\frac{\alpha+1}{2}) \cos \frac{\pi\alpha}{2}}{(\alpha-1) \Gamma(\frac{d+\alpha}{2})}$.

Proof. Let us consider a set of operators $\{\mathbf{B}^\varepsilon : \varepsilon > 0\}$ that act on a continuously differentiable bounded function $(\varphi(x))_{x \in \mathbb{R}^d}$ according to the following rule

$$\mathbf{B}^\varepsilon \varphi(x) = \frac{1}{\varkappa} \int_{|u| \geq \varepsilon} \frac{\varphi(x+u) - \varphi(x)}{|u|^{d+\alpha}} y dy.$$

It is clear that $\lim_{\varepsilon \rightarrow 0+} \mathbf{B}^\varepsilon \varphi(x) = \mathbf{B}\varphi(x)$ for all $x \in \mathbb{R}^d$ and described above functions φ .

Inequalities (6) and (10) allow us to assert that

$$\begin{aligned} & \left| \frac{u}{|u|^{d+\alpha}} (g(t-\tau, x+u, z) - g(t-\tau, x, z)) V(\tau, z, y) |a(z)| \right| \leq \\ & \leq \frac{\text{const}}{|u|^{d+\alpha-1}} \left(\frac{t-\tau}{((t-\tau)^{1/\alpha} + |z-x-u|)^{d+\alpha}} + \frac{t-\tau}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha}} \right) \times \\ & \quad \times \frac{1}{(\tau^{1/\alpha} + |y-z|)^{d+\alpha-1}}. \end{aligned}$$

It is easy to see that the right hand side of this inequality is an integrable function with respect to (u, τ, z) on the set $\{|u| \geq \varepsilon\} \times (0; t) \times \mathbb{R}^d$ for all $t > 0$ and $x \in \mathbb{R}^d, y \in \mathbb{R}^d$. Here we used formula (7). Therefore, we obtain the following equality

$$\begin{aligned} (12) \quad \mathbf{B}_x^\varepsilon \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz = \\ = \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x^\varepsilon g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz, \end{aligned}$$

using Fubini's theorem.

Inequalities (6), (7) and $|\mathbf{B}_x g(t, x, y)| \leq \frac{\text{const}}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$ allow us to assert that the integral $\int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz$ exists. Now we have to pass to the limit as $\varepsilon \rightarrow 0+$ in equality (12) to complete the proof of lemma. \square

Let us prove that the function $G(t, x, y)$ satisfies the Kolmogorov-Chapman equation

$$(13) \quad G(t+s, x, y) = \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz$$

for all $s > 0, t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$. Note, that the function $g(t, x, y)$ satisfies equation (13).

Put $U(s, x, \varphi) = \int_{\mathbb{R}^d} G(s, x, y) \varphi(y) dy, \quad u(s, x, \varphi) = \int_{\mathbb{R}^d} g(s, x, y) \varphi(y) dy, \quad \text{and}$
 $W(s, x, \varphi) = \int_{\mathbb{R}^d} V(s, x, y) \varphi(y) dy, \text{ where } \varphi \in C_b(\mathbb{R}^d).$

Note, that the function $W(t, x, \varphi)$ is the unique solution of the following equation

$$(14) \quad W(t, x, \varphi) = W_0(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz,$$

where $W_0(s, x, \varphi) = \int_{\mathbb{R}^d} V_0(s, x, y) \varphi(y) dy.$

Then the function $U(s, x, \varphi)$ can be given by the equality (see (11))

$$U(t, x, \varphi) = u(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz$$

Now, let us find the function $U(t + s, x, \varphi)$. We have

$$\begin{aligned} U(t + s, x, \varphi) &= u(t + s, x, \varphi) + \int_0^{t+s} d\tau \int_{\mathbb{R}^d} g(t + s - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz = \\ &= \int_{\mathbb{R}^d} g(s, x, y) u(t, y, \varphi) dy + \int_{\mathbb{R}^d} g(s, x, y) dy \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, y, z) W(\tau, z, \varphi) |a(z)| dz + \\ &\quad + \int_t^{s+t} d\tau \int_{\mathbb{R}^d} g(t + s - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz = \\ &= \int_{\mathbb{R}^d} g(s, x, y) U(t, y, \varphi) dy + \int_0^s d\tau \int_{\mathbb{R}^d} g(s - \tau, x, z) W(t + \tau, z, \varphi) |a(z)| dz. \end{aligned}$$

Therefore, the function $W_t(s, x, \varphi) = W(t + s, x, \varphi)$ satisfies equation (14), where the function φ is replaced by $U(t, \cdot, \varphi)$. Then $W(t + s, x, \varphi) = W(s, x, U(t, \cdot, \varphi))$ and we arrive at the equality $U(t + s, x, \varphi) = U(s, x, U(t, \cdot, \varphi))$ or, what is the same,

$$\begin{aligned} \int_{\mathbb{R}^d} G(t + s, x, y) \varphi(y) dy &= \int_{\mathbb{R}^d} G(s, x, z) \int_{\mathbb{R}^d} G(t, z, y) \varphi(y) dy dz = \\ &= \int_{\mathbb{R}^d} \varphi(y) dy \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz. \end{aligned}$$

Then relation (13) is proved because the function φ is an arbitrary bounded continuous one.

Next, we get $\int_{\mathbb{R}^d} G(t, x, y) dy \equiv 1$ from (2) and (3), because the equalities

$$\int_{\mathbb{R}^d} g(t, x, y) dy = 1 \quad \text{and} \quad \int_{\mathbb{R}^d} V_0(t, x, y) dy = \left(\mathbf{B}_x \int_{\mathbb{R}^d} g(t, x, y) dy, e(x) \right) = 0$$

for all $t > 0$, $x \in \mathbb{R}^d$ are obvious, and the uniqueness of the solution of equation (3) leads us to the identity $\int_{\mathbb{R}^d} V(t, x, y) dy \equiv 0$. \square

Remark 2.2. The family of operators $(T_t)_{t>0}$ defined for any bounded continuous function φ on \mathbb{R}^d by the equality $T_t\varphi(x) = \int_{\mathbb{R}^d} G(t, x, y) \varphi(y) dy$, $t > 0$, $x \in \mathbb{R}^d$, indeed constitutes a semigroup generated by the operator $\mathbf{A} + (a(x), \mathbf{B})$. But, there is no Markov process in \mathbb{R}^d corresponding to this semigroup because it does not preserve the property of a function to take on only non-negative values (see, for example, [1]).

3. THE CAUCHY PROBLEM

First, let the function a be smooth enough. For the simplicity we suppose that $a \in C_0^\infty(\mathbb{R}^d)$ (this is the space of all \mathbb{R}^d -valued infinitely differentiable functions on \mathbb{R}^d with compact support). Thus, the function

$$\begin{aligned} U(t, x) &= \int_{\mathbb{R}^d} \varphi(y) G(t, x, y) dy = \\ &= \int_{\mathbb{R}^d} \varphi(y) g(t, x, y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, y) \int_{\mathbb{R}^d} V(\tau, y, z) \varphi(z) dz |a(y)| dy \end{aligned}$$

is the unique (in the class of functions that tends to zero at infinity) solution of the Cauchy problem (8) with $f(t, x) = |a(x)| \int_{\mathbb{R}^d} V(t, x, z) \varphi(z) dz$.

Now we note that $V(t, x, y) = (\mathbf{B}_x G(t, x, y), e(x))$. Then

$$f(t, x) = \int_{\mathbb{R}^d} (\mathbf{B}_x G(t, x, z), a(x)) \varphi(z) dz = (a(x), \mathbf{B}_x U(t, x))$$

and the function $U(t, x)$ is a solution of the Cauchy problem

$$(15) \quad \begin{cases} \frac{\partial u(t, x)}{\partial t} = \mathbf{A}_x u(t, x) + (a(x), \mathbf{B}_x u(t, x)), & t > 0, x \in \mathbb{R}^d, \\ \lim_{t \rightarrow 0^+} u(t, x) = \varphi(x), & x \in \mathbb{R}^d \end{cases}$$

for an arbitrary continuous bounded function $(\varphi(x))_{x \in \mathbb{R}^d}$.

The next statement will allow us to construct a generalized solution of the Cauchy problem.

Theorem 3.1. *Let a and \tilde{a} be given functions that satisfy the conditions of Theorem 2.1. Denote by G and \tilde{G} the solutions of (1) corresponding to the functions a and \tilde{a} , respectively. Then the inequality*

$$|G(t, x, y) - \tilde{G}(t, x, y)| \leq H_T \|a - \tilde{a}\|_p \frac{t^{1 - \frac{d}{\alpha p}}}{(t^{\frac{1}{\alpha}} + |y - x|)^{d + \alpha - 1}}$$

(or $|G(t, x, y) - \tilde{G}(t, x, y)| \leq H_T \|a - \tilde{a}\|_\infty \frac{t}{(t^{\frac{1}{\alpha}} + |y - x|)^{d + \alpha - 1}}$, if $p = +\infty$)

is held on each domain $(0, T] \times \mathbb{R}^d \times \mathbb{R}^d$ for $T < +\infty$, where the positive constant H_T depends on $c, \alpha, \|a\|_p, \|\tilde{a}\|_p$ and T .

Proof. We will consider the case of finite values of p . The case $p = +\infty$ is similar to this one.

It is easy to see that

$$(16) \quad G(t, x, y) - \tilde{G}(t, x, y) = \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) W(\tau, z, y) dz,$$

where $W(\tau, z, y) = V(\tau, z, y)|a(z)| - \tilde{V}(\tau, z, y)|\tilde{a}(z)|$ and the functions V and \tilde{V} are solutions of equation (3) with the functions a and \tilde{a} , respectively. We can write down the following equality

$$(17) \quad \begin{aligned} W(t, x, y) &= W_0(t, x, y) + |a(x)| \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) W(\tau, z, y) dz + \\ &+ \int_0^t d\tau \int_{\mathbb{R}^d} W_0(t - \tau, x, z) \tilde{V}(\tau, z, y) |\tilde{a}(z)| dz, \end{aligned}$$

taking into account equality (3), where $W_0(t, x, y) = (\mathbf{B}_x g(t, x, y), a(x) - \tilde{a}(x))$.

Let us estimate the first and the third items on the right-hand side of equality (17). The following inequality

$$|W_0(t, x, y)| \leq |\mathbf{B}_x g(t, x, y)| |a(x) - \tilde{a}(x)| \leq \frac{N}{c\alpha} \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}}$$

is easily derived from formulas (4) and (9) for $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t > 0$. Using inequalities (7), (10) and the previous inequality one can show that for $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t \in (0, T]$ and every $T > 0$

$$\left| \int_0^t d\tau \int_{\mathbb{R}^d} W_0(t - \tau, x, z) \tilde{V}(\tau, z, y) |\tilde{a}(z)| dz \right| \leq K_T |a(x) - \tilde{a}(x)| \frac{t^{1/\alpha}}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}},$$

where K_T is some positive constant, which depends on T , maybe.

Thus, we can write down the following inequality

$$(18) \quad \begin{aligned} |W(t, x, y)| &\leq Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}} + \\ &+ \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{|W(\tau, z, y)|}{((t - \tau)^{1/\alpha} + |z - x|)^{d + \alpha - 1}} dz \end{aligned}$$

that holds true for $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$, $t \in (0, T]$ and every $T > 0$, where $Q_T > 0$ is some constant, which maybe depends on T .

Iterating inequality (18) we obtain for $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$, $t \in (0, T]$ and every $T > 0$

$$(19) \quad |W(t, x, y)| \leq \sum_{k=0}^{\infty} R_k(t, x, y),$$

where $R_0(t, x, y) = Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}}$ and for $k \geq 1$ the following recurrence relation $R_k(t, x, y) = \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{R_{k-1}(\tau, z, y)}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha-1}} dz$ holds.

Using Hölder's inequality and inequality (7) one can show by induction on k that the function R_k for $k = 1, 2, \dots$ satisfies the inequalities

$$\begin{aligned} 0 \leq R_k(t, x, y) &\leq Q_T \left(\frac{N}{c\alpha} \right)^k C^{k-1/p} \left(2B \left(1, \frac{p-d-\alpha}{\alpha(p-1)} \right) \right)^{1-1/p} \times \\ &\quad \times \left(B \left(\frac{1}{\alpha}, 1 + \frac{p-d}{\alpha p} \right) + B \left(1, 1 + \frac{2p-d}{\alpha p} \right) \right) \times \dots \\ &\quad \times \left(B \left(\frac{1}{\alpha}, 1 + \frac{(k-1)p-d}{\alpha p} \right) + B \left(1, 1 + \frac{kp-d}{\alpha p} \right) \right) \times \\ &\quad \times \frac{t^{(kp-d)/(\alpha p)}}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} \|a - \tilde{a}\|_p. \end{aligned}$$

Hence, we conclude that the series in inequality (19) converges uniformly in $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$ and locally uniformly in $t > 0$. Therefore, the following inequality

$$|W(t, x, y)| \leq M_T \frac{\|a - \tilde{a}\|_p}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} t^{\frac{p-d}{\alpha p}} + Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}}$$

holds for $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$, $t \in (0, T]$ and every $T > 0$, where M_T and Q_T are some positive constants, which maybe depend on T .

Some not difficult calculations using formulas (6),(7), (16) and Hölder's inequality lead us to the assertion of the theorem. \square

Corollary 3.1. *Let $\varphi \in C_b(\mathbb{R}^d)$ and G, \tilde{G} be as in Theorem 2.1. Put*

$$U(t, x) = \int_{\mathbb{R}^d} G(t, x, y) \varphi(y) dy, \quad \tilde{U}(t, x) = \int_{\mathbb{R}^d} \tilde{G}(t, x, y) \varphi(y) dy.$$

Then the following inequality $|U(t, x) - \tilde{U}(t, x)| \leq L_T \sup_y |\varphi(y)| \|a - \tilde{a}\|_p$ is held for $x \in \mathbb{R}^d$, $0 < t \leq T$. Here L_T is some positive constant, that maybe depends of T .

Now, let $a(x)$ be a given \mathbb{R}^d -valued function on \mathbb{R}^d satisfying the condition $\|a\|_p < \infty$ for some $p > d + \alpha$. Then there exists a sequence of functions $a_n \in C_0^\infty(\mathbb{R}^d)$, such that $\|a_n - a\|_p \rightarrow 0$ as $n \rightarrow \infty$. According to Corollary 3.1, we can defined the function $U(t, x)$ by the equality $U(t, x) = \lim_{n \rightarrow \infty} U_n(t, x)$, where $U_n(t, x)$ is the solution of the Cauchy problem (15) corresponding to the function a_n . The statement of Theorem 3.1 means that $U(t, x) = \int_{\mathbb{R}^d} G(t, x, y) \varphi(y) dy$, where $G(t, x, y)$ is the perturbation (corresponding to the function a) of the transition probability density of the symmetric stable process (see Definition 1.1). We say exactly in this sense that the function $U(t, x)$ is a generalized solution of the Cauchy problem (15).

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